A New Candidate Rule for the Game of Two-dimensional Life

Jean-Claude Heudin

International Institute of Multimedia,
Pôle Universitaire Léonard de Vinci,
92916 Paris La Défense, France

Abstract. This paper introduces a new candidate rule for a game of two-dimensional Life “worthy of the name.” The cellular automaton is defined in a formal sense and presented using qualitative and quantitative approaches. Various natural stable and oscillating patterns, including a propagating glider, are described.

1. Introduction

The two-dimensional cellular automaton (CA) Life, originally described in [6, 7], has been presented in a large number of publications. It shows complex dynamics [14] and has been proven capable of supporting universal computation [5]. According to several authors [13, 14], Life seems to be an exception in the huge space of possible two-dimensional transition rules. Few variants have been mentioned [5, 14] but never clearly identified or carefully described. Therefore, most authors have concluded that Life is in fact unique.

The most recent variation on this theme has been a series of articles by Carter Bays [1–4]. Bays has expanded Life into three dimensions and proposed a general definition for the set of possible rules [1]. Each rule can be written in the form \( E_bE_hF_bF_h \) where \( E_b \) is the minimum number of living neighbor cells that must touch a currently living cell in order to guarantee that it will remain alive in the next generation. \( F_b \) is the minimum number touching a currently dead cell in order that it will come to life in the next generation and \( E_h \) and \( F_h \) are the corresponding upper limits. These rules are called the “environment” and “fertility” rules. According to this notation, Conway’s Life would be written “Life 2333,” that is \( E_b = 2, E_h = 3, F_b = 3, \) and \( F_h = 3. \)

*Electronic mail address: Jean-Claude.Heudin@devinci.fr.

1A good place to see what is widely available is the Usenet interest groups on CA: comp.theory.cell-automata and cellular-automata@buphy.bu.edu.

© 1996 Complex Systems Publications, Inc.
While performing a systematic study of two-dimensional Life CA [10], another rule candidate for a game of Life worthy of the name has been discovered. This rule, called Life 1133, satisfies the following two criteria defined in [4].

1. Primordial soup experiments must exhibit bounded growth. This means than an initial random “blob” must eventually stabilize and cannot grow without limit.

2. A glider must exist and occur “naturally,” that is, it must be discoverable by repeatedly performing primordial soup experiments.

The first criterion is satisfied since all primordial soup experiments we have performed shrunk and stabilized or disappeared, as we show in section 2. The second criterion is also satisfied since we have discovered a propagating glider that occurs naturally. The glider is described in section 3 along with other natural structures of Life 1133.

2. Qualitative and quantitative analysis

2.1 Experimental environment

We have based our experiments on a toroidal universe, consisting of a 64\times64 lattice with a finite-state automaton at each lattice site. Each primordial soup experiment was initialized randomly to a 50 percent density of living cells (Figure 1). Such disordered configurations are typical members of the set of all possible configurations and, therefore, patterns generated from them are typical of those obtained with any initial state. Thus, the presence of structures in these patterns is an indication of self-organization in the CA [16].

![Figure 1: A sample random initialization.](image)
A New Candidate Rule for the Game of Two-dimensional Life

At each generation we have recorded the distribution of fired rules for a deeper understanding of the dynamical properties of the system. In this framework, we have written the Life rules using the following (equivalent) definition.

Let $S_t$ be the state of an arbitrary cell at generation $t$, and $N_t$ the number of its living neighbors. Then, the general Life transition rule can be defined by:

$$
\begin{align*}
\text{if} & \quad (N_t \geq F_b) \& (N_t \leq F_h) \rightarrow S_{t+1} = 1, & (R1) \\
\text{else if} & \quad (N_t \geq E_b) \& (N_t \leq E_h) \rightarrow S_{t+1} = S_t, & (R2) \\
\text{else} & \quad S_{t+1} = 0. & (R3)
\end{align*}
$$

That is, for Life 1133:

$$
\begin{align*}
\text{if} & \quad N_t = 3 \rightarrow S_{t+1} = 1, & (R1) \\
\text{else if} & \quad N_t = 1 \rightarrow S_{t+1} = S_t, & (R2) \\
\text{else} & \quad S_{t+1} = 0. & (R3)
\end{align*}
$$

2.2 Qualitative results

The global behavior of Life 1133 looks like that of Life 2333, but with shorter transients. For almost all initial disordered configurations, the density decreases rapidly and tends to an equilibrium limit. In all cases, most sites are seen to “die” after a small finite time. However, stable or periodic patterns which persist for an infinite time are generally formed and, in a few cases, propagating structures have emerged. Section 3 describes more carefully some of these natural structures.

Figure 2 gives an example of a typical configuration of Life 1133 after a few time steps. Figure 3 shows a typical ending configuration with both
stable and period 2 oscillators. In most cases this kind of pattern occurs before generation 50, to be compared with the very long transients of Life 2333 (generally more than 1000 generations in the same conditions).

2.3 Fired rules distribution

Before proceeding further, we should examine the distribution of fired rules for Life 1133 and compare it to that of LIFE 2333. Figure 4 gives results for the first 100 generations for both CA. Summing up our results, we obtain the given plots. For all experiments performed, most “alive” cells die from overpopulation or isolation (R3) and the systems rapidly stabilize with the ordering R3 > R2 > R1.
Our convention for the transition rule emphasizes the role of $R_2$ acting as a “memory rule” which significantly influences the dynamical behavior of both CA. All experiments have revealed the same ordering of rules, that is, $R_3 > R_2 > R_1$ with $R_1 \neq 0$, which seems to be a property of Life Class IV CA, as already mentioned in a previous study [9].

2.4 Mean field approximation

The mean field theory describes how CA act on probability measures [8]. According to this theory, we note with $x$ the probability that a cell is alive and
with $1 - x$ the probability that it is dead. If we assume that the probability for a cell to be in a given state is uncorrelated with the states of other cells, then the probability for a block is just the product of the probabilities of the cells in the block.

Thus, for Life 2333, we obtain the following mean field equation:

$$y = C_8^3 \cdot x^3 \cdot (1 - x)^6 + C_8^2 \cdot x^3 \cdot (1 - x)^6 + C_8^3 \cdot x^4 \cdot (1 - x)^5,$$

that is,

$$y = 84 \cdot x^3 \cdot (1 - x)^6 + 56 \cdot x^4 \cdot (1 - x)^5.$$

With the same conditions, the mean field equation for Life 1133 is:

$$y = C_8^3 \cdot x^3 \cdot (1 - x)^6 + C_8^3 \cdot x^4 \cdot (1 - x)^5 + C_8^4 \cdot x^2 \cdot (1 - x)^7,$$

that is,

$$y = 56 \cdot x^3 \cdot (1 - x)^6 + 56 \cdot x^4 \cdot (1 - x)^5 + 8 \cdot x^2 \cdot (1 - x)^7.$$

Figure 5 shows a graph of these two probability curves together with the diagonal line of unchanged probability. Both curves cross the diagonal at slightly more than tangency and are quadratic at the origin.

2.5 Lambda value

There has been a growing feeling that Wolfram's classification is a scale measuring the distribution of periodic cycles in CA with class IV forming a transition region between class II (short periods and lengths) and class III (chaotic regime). In this framework, Cristopher Langton proposed a parametrization scheme on the CA rule space based on the $\lambda$ parameter [11].
According to the definition of $\lambda$, Life 1133 is characterized by a value in the same vicinity:

$$\lambda_{2333} = 0.273438 \quad \text{and} \quad \lambda_{1133} = 0.234375.$$

This would suggest the correctness of the $\lambda$ parametrization. However, we have also found class I (e.g., Life 2255), class II (e.g., Life 6633) and class III (e.g., Life 1233) CA in the same vicinity [10]. As first observed in [12], it seems that the $\lambda$ parameter alone is insufficient for locating specific regimes precisely, even in a subset of the CA rule space like Life.

3. A review of common natural structures

3.1 Fixed structures

The low density of Life 1133 after a few time steps is compensated for by the rich variety and symmetry of simple Life forms. All the structures shown in this section occur naturally.

The first kind of structure includes stable patterns that never change. They represent the commonest objects of Life 1133. Figure 6 gives a selection of these structures, including the “block”: a four-cell pattern formed by a two-by-two square which is one of the few structures in common with Life 2333. The most common object of Life 1133 is the “small block” consisting of two adjacent living cells.

3.2 Period 2 oscillators

Life 1133 shows a rich variety of oscillators. Most of them have a period of two. Figure 7 gives a selection of these objects. The fourth oscillator in the upper part of the figure leads to other forms, some of them occurring naturally, such as the first oscillator in the lower part of the figure. We have called this oscillator the “barber pole” recalling the same kind of structure from Life 2333. It is an oscillator that may be stretched to any length, making it as large as desired (Figure 8). Only small versions occur spontaneously.
One of the most interesting features of Life 1133 seems to be its symmetry property. All structures that have been discovered so far exhibit symmetry of one form or another: reflection, rotation, etcetera.

3.3 Other oscillators with greater periods

Oscillators with periods other than two have been found, but all with an even period. Figure 9 shows a selection of period 4 oscillators. When generated on a high-speed computer, these oscillators create convincing illusions of three-dimensional rotary motion.

One of the most beautiful and interesting objects is a symmetric combination of four simple period 4 oscillators (Figure 10). This arrangement recalls the well known “traffic light” from Life 2333, but with a period of four instead of two and a more sophisticated pattern. With a fast execution speed, this structure looks like a “twinkling star.”

A quite common oscillator has a period of ten. The second five phases are the rotated and mirrored images of the first five phases. Figure 11 shows this oscillator that we have named the “alien clock.”

3.4 Propagating glider

One of the criterion for Life 1133 to be a game of life worthy of the name is the existence of a natural propagating glider. The glider of Life 1133 was discovered only after ten primordial soup experiments. However, it seems
that it is less common than the one of Life 2333, mainly because of the relative short transients of Life 1133.

The glider appears to creep something like an amoeba, changing its shape as it goes. Like Conway’s glider, it assumes four different phases and moves at the same speed: one cell per four generations, or, in other terms, one-quarter cell per generation. Unlike Conway’s glider, it moves horizontally or vertically instead of diagonally. Figure 12 shows the four states. When state one is encountered again, the glider will have moved one cell forward.

The behavior of gliders interacting with other artifacts represents the foundation for implementing complicated structures including a universal Turing machine. Therefore, the investigation of the glider of Life 1133 in more detail is an important part of this study.
4. Glider-based computing

4.1 Collisions

What happens when a glider collides with another object? The number of possible objects leads to a large number of possible collisions between a glider and other objects. One would expect that, in most cases, the result of such events is the annihilation of both objects. This is the case, for example, when two gliders move towards the same point as shown in Figure 13. This collision is particularly useful for implementing vanish reactions in glider streams (see section 4.3).

However, in some other cases, the collision leads to the birth of objects that do not fade instantly. As an example, Figure 14 shows a glider colliding with a block. The collision results in two debris: a new block and a period 2 oscillator.

Figure 13: A collision between two gliders leads to the annihilation of all living cells. The last configuration \( (t_{10}) \), consisting of an empty array, is not shown here.

Figure 14: A collision between a glider and a block.
Figure 15: The collision between a glider and a small block produces the 6-phase fighter.

Figure 16: The 6-phase fighter in action.

The subject of collision is more complicated than might be thought, for there are usually many different ways that two objects can collide: respective positions and phases almost always make a difference.

One of the most interesting collisions occurs when a glider collides with a small block. This configuration produces a new glider type consisting of both objects (Figure 15). We have named this glider the “fighter,” because of its robustness and the fact that it can fire a “torpedo” on a line of small blocks and destroy any object placed at the end of the line (Figure 16). Besides this amusing comparison, it gives a clear example of properties of Life 1133 for constructing objects showing complicated or surprising behaviors.

4.2 Speed of light

Life’s rules limit the speed of propagating structures. The maximum speed at which any information can be transmitted across the Life plane is one cell per generation in any direction. This can be viewed as the counterpart of the speed of light in the real world and is often called by that name. It is quite easy to find a pattern propagating at this maximum speed in Life 1133. As seen in the previous section with the fighter (Figure 16), a simple pulse on a line of small blocks produces that behavior (Figure 17).
4.3 Universal computation

The existence of a glider suggests that, similar to Conway’s Life, Life 1133 could be capable of universal computation. In a constructive proof of universality [6], a stream of regularly spaced propagating gliders represents a string of bits. In such a stream, the presence of a glider at a given position represents a “1” and absence represents a “0.” Based on such streams, the implementation of a single logical gate (a NAND or a NOR gate) is required to be able to design any digital machine, including a universal Turing machine.

Useful configurations for implementing such a logical element include the vanish reaction when two gliders collide (see section 4.1) and the “star gate:” a pattern composed of two twisters that destroy any glider in a stream while preserving its own structure (Figure 18). In practice, there are further elements required such as elements that will turn a signal stream by right angles, but we do not go into the details of these elements in this paper.

A series of experiments was performed in order to find a “glider gun:” a periodic structure that produces the required steady stream of gliders. We have found many configurations producing a glider (Figure 19), but we must point out that we have not yet discovered this crucial element. Note that Carter Bays has not found such an object, or at least reported one, during several years of extensive research on three-dimensional Life CA. However, the study of Life 1133 is still recent and is currently undergoing intense investigation.

5. Implementation

Many implementations of Life and CA tools are available for many platforms (see H. A. Gutowitz’s FAQ Life page for a good introduction and links to these tools). Life 1133 was found using a very simple CA applet designed

\[\text{http://alife.santafe.edu/alife/topics/cas/ca-faq/lifefaq/lifefaq.html}\]
Figure 18: The star gate (two twisters) destroys any glider that try to pass.

Figure 19: Two patterns producing a glider.

with the Java Development Kit 1.0.2. Our motivation was to use a modern object-oriented and highly-portable code accessible to anyone with at least a Java-enabled browser. The applet source is available on the World Wide Web,\(^3\) Another Java-based implementation of Life designed by Paul Callahan with a large database of patterns is also available.\(^4\) Yet another Java-based implementation provides a huge universe (1 million × 1 million cells) and a very fast algorithm.\(^5\)

\(^3\)http://www.devinci.fr/iim/jch/
\(^4\)http://www.cs.jhu.edu/~callahan/lifepage.html
\(^5\)http://www.mindspring.com/~alanh/life/
6. Conclusion

Many variants of Conway’s rule of Life have been tried without any having been reported as being worthy of further attention. In this paper, we have presented another rule for a game of Life worthy of the name. Life 1133 shares the same global properties of Life 2333 but with shorter transients. It shows a rich universe of small symmetric stable and oscillating patterns including a propagating glider. This is quite surprising, since class IV CA generally combine complex patterns and very long transients. The next phase of this study will focus on the discovery of a glider gun in order to make a constructive proof of universality.

Conway’s Life is the ideal example of Wolfram’s class IV automaton for two-dimensional two-states CA [13]. Life 1133 is another example of such an automaton. One can consider it as a “trivial variant” of Life 2333, since the only difference is the value used by the “environment” rule (R2). However, the discovery of Life 1133 is important since it clearly shows that other rules for a game of Life exist that require further attention.

References

A New Candidate Rule for the Game of Two-dimensional Life


